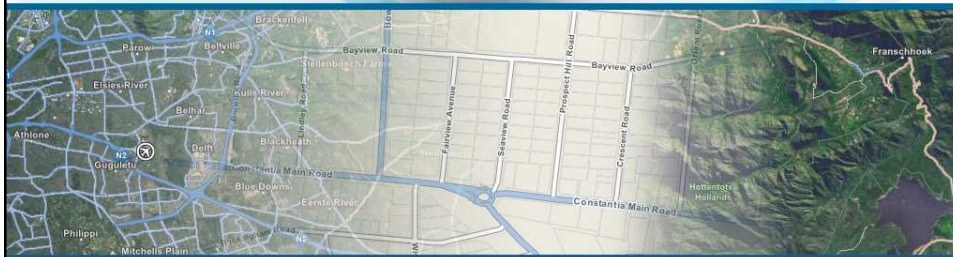


Standards that make Innovation Possible

ITS and GIS standards to support autonomous driving

UNWGIC-meeting 2018-11-20, Deqing



21 November 2018
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Agenda

1. Four ITS-trends
2. Standards as platform for innovation
3. Please disrupt us!

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Four ITS-Trends

AUTONOMOUS VEHICLES

- Self contained cars
- Driver relief and increased traffic safety

CONNECTED CAR/COOPERATIVE ITS

- Self contained and connected
- Effortless negotiation of traffic and less emission

MOBILITY AS A SERVICE

- Sharing all transport resources
- Seamless travel – fewer vehicles

EMISSION FREE VEHICLES

- Less complicated
- No local emissions

Source: compiled from the internet-ITS Norway

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3 GOOD HEALTH AND WELL-BEING

9 INDUSTRY, INNOVATION AND INFRASTRUCTURE

11 SUSTAINABLE CITIES AND COMMUNITIES

13 CLIMATE ACTION

17 PARTNERSHIPS FOR THE GOALS

ZERO ACCIDENTS

RECLAIMED LAND

ZERO EMISSION

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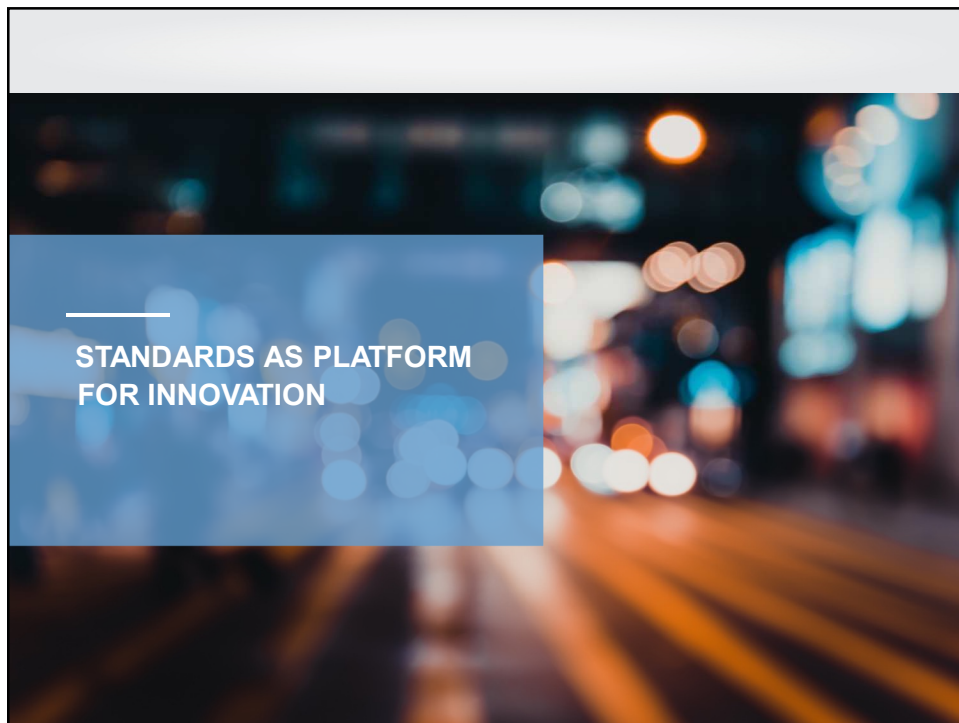
Self-driving cars

Source: Compiled from the internet - ITS Norge, Soren Steira



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Geometry based on maps or sensors?

Diagram illustrating various sensor types and their applications in a road environment. The diagram shows a cross-section of a road with different layers and sensors. Labels include: Gang- og sykkelveg, A-føring, A-føring, and Føring. The diagram also shows various sensor types like GPS, LiDAR, and cameras, and their applications in different road environments.

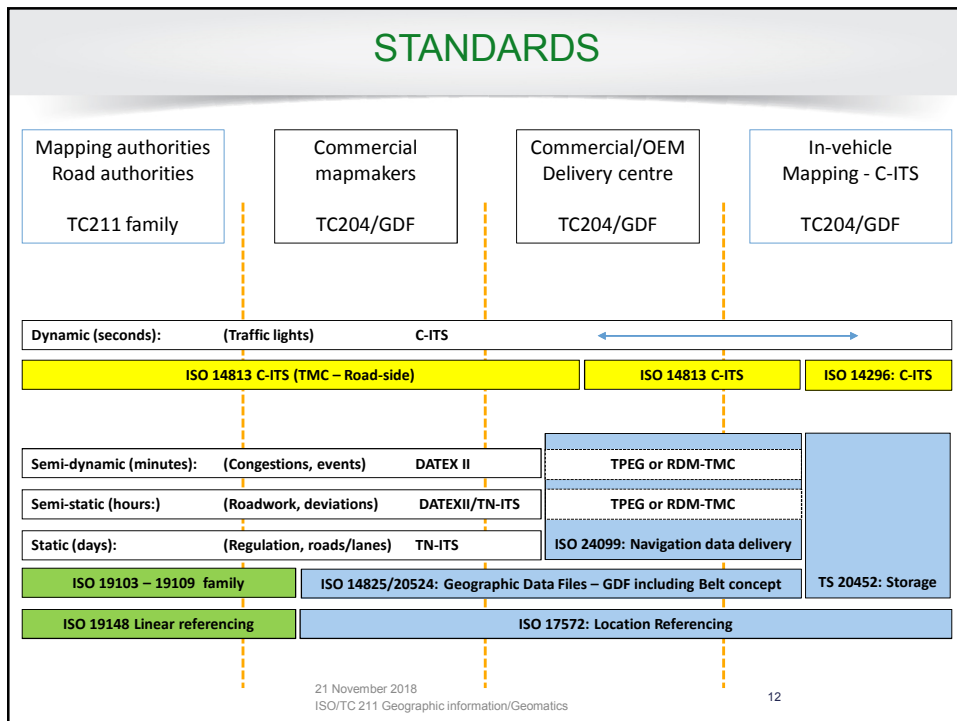
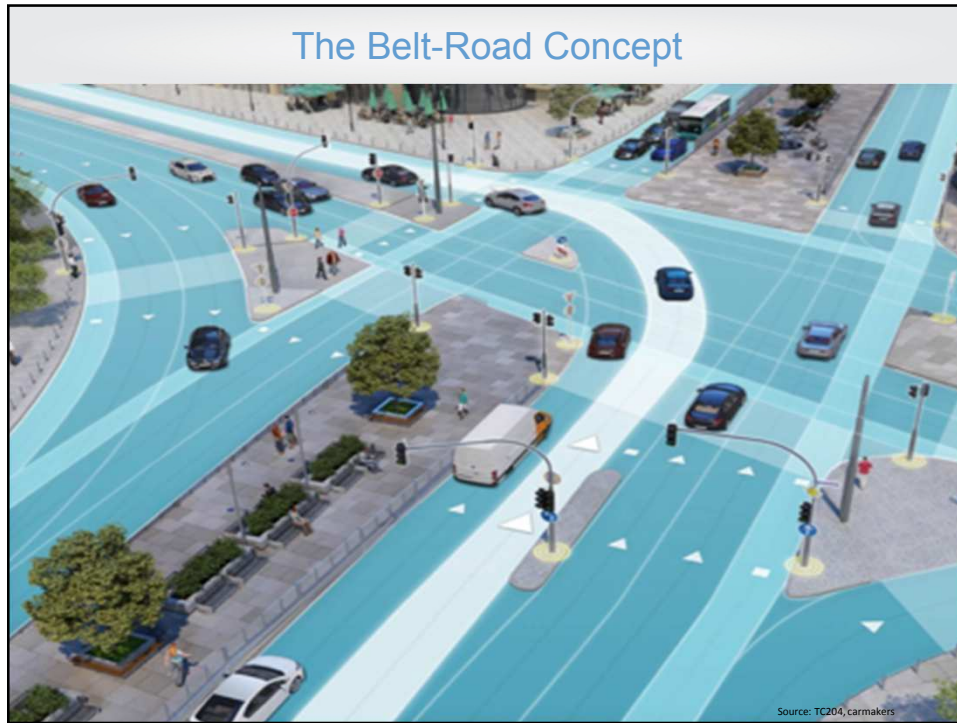
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Dynamic Map Concept – Services – ISO/NDS

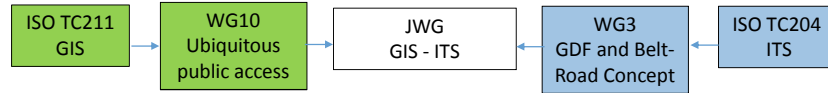
Diagram illustrating the 'Linked layers' concept. It shows a stack of map layers: Basic Map, Link, and Link. The layers are connected by arrows, indicating a flow of information from the basic map to the dynamic layers.

Diagram illustrating the 'Dynamic Map Concept – Services – ISO/NDS'. It shows a flow of information between various stakeholders and vehicles. The stakeholders include OEM, public Back-offices, Mapmakers, and Authorities. The vehicles are represented by a car and a truck. The flow of information is shown as a vertical line with arrows pointing to and from the vehicles. The services provided are Position, Map, Navigation, Regulations, and Events/conditions. The process is described as 'Creating and sharing maps using on-board and street sensors'.

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Cooperation



WI 1: Gap-analysis GDF and TC211 based model – TR

- Redefine the GDF-model based on TC211-standards
- Enable handling of very detailed and accurate geometries
- Enable map-data exchange between all actors
- Align with data models based on ISO 19100 like TISA, TN-ITS, Datex II, etc.

WI 2: Linear/Location references – TR

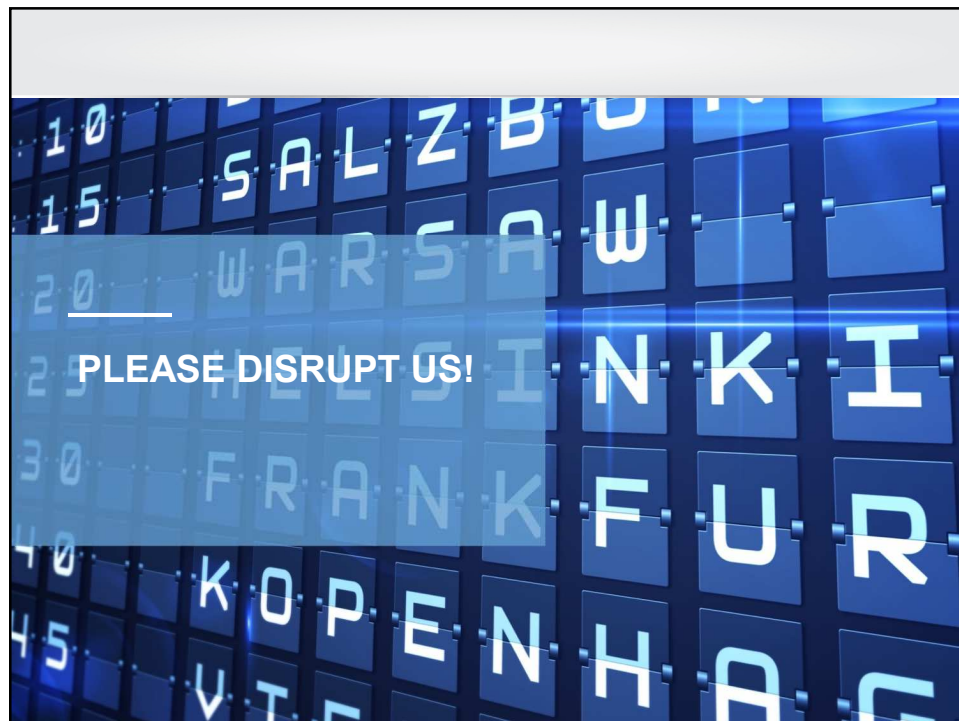
- Support for the belt road concept, shareable database and dynamic data
- Input to the revision of 19148

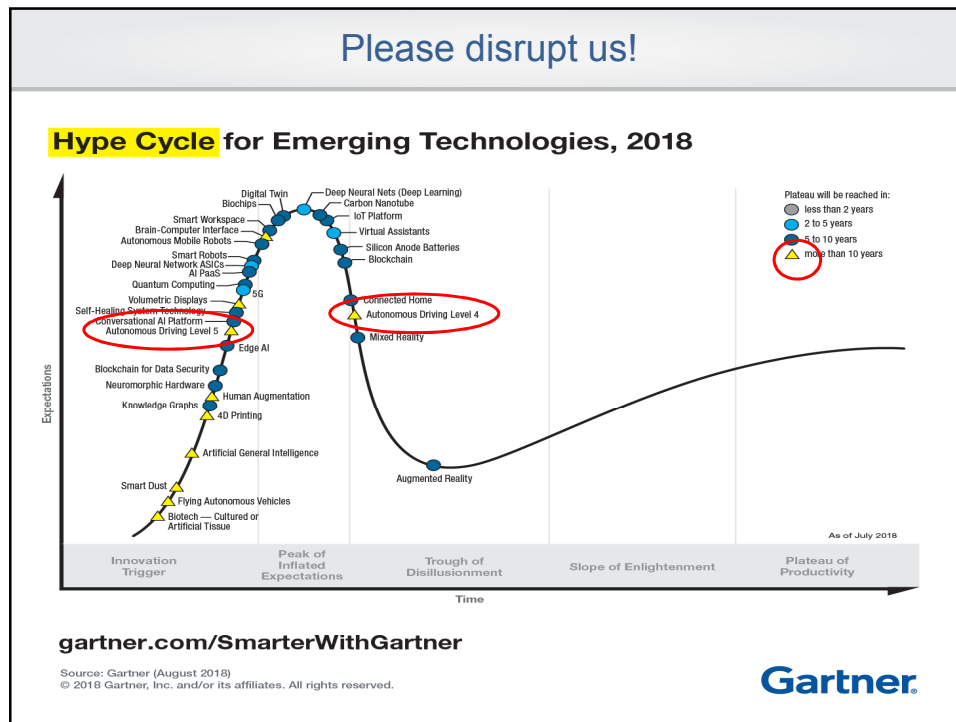
WI 3: Terminology – investigation by TMG

- JWG members will investigate terminology issues between the two TCs
- Report in the form of a standing document

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If not... we have a lot of work in front of us!

A truly autonomous ecosystem of vehicles requires:

- A shared, detailed and accurate geometry
- Creation of belts – planned and on the spot
- Cooperation
- New regulations and standards
- A robust communication system
- Validation and certification procedures
- Redundant 24/7/365 operation

Innovate to make it work!

Questions?